





METROFORM

Crankshaft & Camshaft Metrology



Designed for Perfection





Metroform

Crankshaft & Camshaft Metrology System

Measurement and analysis of precision crankshaft and camshaft



Features :

- Precision flat granite bed for high degree of Thermal or structural stability.
- High precision linear guiding system
- High precision carbide tip followers
- Window based software for easy program creation
- and editing facility.Easy diagnosis system for fault finding

MetroForm is a three axis CNC vertical metrology system specially design for Crank and Camshaft measurements applications. Metroform system consists of Precision rotary spindle, two precision linear axes and the adjustable tail stock for easy loading of part in vertical position. The machine is constructed using granite base and isolated with anti vibration mount, this minimal foot print design allows the easy installation in production shop and inspection room. The MetroForm system integrated with advance data acquisition electronics and powerful MetroLab Software.

MetroLab is user friendly and easily programmable for various crankshaft and camshaft geometry. The system can measure the drawing parameters for the crank and cam shaft such as Linear, Angular and Form parameters. The software has an advance features such as sector roundness, lobbing and chatter analysis. MetroLab software display the results in graphical and tabulated formats, the measurement reports can be stored in PDF file format and easily recall for future references.

- High resolution glass encoder system for both rotary and radial axis facilitates to have highest precise measurement data.
- Interchangeable hardened centres for tail stock and head stock.
- Different user level CNC and motorised operation.

Software feature

- Auto compensation for follower wear
- Auto detection of oil hole and automatic data filtration for roundness
 - User-friendly programming
 - Report customisation
 - Graphical representation
 - User level operation mode

CRANK SHAFT MEASURING PARAMETERS	System Specifications:	Metroform 360	Metroform 660	Metroform 1060
 AT MAIN JOURNAL Diameter ●Length ● Width ● Concentricity ●Eccentricity Roundness ● Sector Roundness ● Run-out Radial & Face w.r.t. centre axis, Part journal axis ● Straightness ● Cylindericity Face Perpendicularity ● Lobbing ● Chatter analysts 	Part length	300 mm	600 mm	1000 mm
	Swing diameter	150 mm	200 mm	200 mm
	Follower stroke	120 mm	150 mm	150 mm
	Part weight	75 kg	100 kg	100 kg
AT PIN JOURNAL • Diameter, Length, width • Roundness • Sector Roundness • Straightness • Cylindericity • Parallelism • Index angle, Index position (angular linear) • Lobbing • Chatter analysts	Spindle rpm	6 rpm	6 rpm	6 rpm
	(Programmable)			
	Radial Resolution	0.1 µm	0.1 µm	0.1 µm
AT FLANGE ● Diameter● Roundness● Face run-out ● Run-out Radial &	Axil Resolution	0.1 µm	0.1 µm	0.1 µm
	Angular Resolution	0.0005 deg	0.0005 deg	0.0005 deg
Face w. r. t. centre axis, part journal axis • Face Perpendicularity				
CAMSHAFT MEASURING PARAMETERS	Machine Dimensions :			
Roundness (LSC, MZC) Surface Chatter Lift / Lift Error	Height	1300 mm	1600 mm	2000 mm
• Index Angle to Reference(s) • Cylindricity • Taper • Center Deviation	Width	550 mm	700 mm	700 mm
Base Circle Radius Diameter Eccentricity Velocity Lobing.	Depth	425 mm	425 mm	425 mm
 Radius	Weight	270 kg	400 kg	470 kg
Radius of Curvature Pressure Angle	(Design / Specifications subjects to change without notice)			



Octago



Octagon Metro-Form Horizon and Octagon Metro-Form Multi Scan are metrology systems designed for rigorous metrological analysis of cylindrical parts specially automobile camshafts by using computerised analysis. Horizon series of Metroform provides facilitates easy loading / unloading of the component.

The MetroLab software is designed to measure multiple lobes for its various dimensional parameters including lobe tip angles. Cam lobe data is automatically captured by rotating camshaft manually or with motorised spindle. Measurement can be taken using a round or flat measuring probes. Data is mathematically converted to the correct engine follower type and size. The machine is designed for standard room as well as shop floor measurements.



- Radius
- Radius of Curvature
- Runout (radial)
- Pressure Angle
- Acceleration
- - Jerk
- Compare base circle radius, run-out and lobe tip angles to design data showing tolerance limits
- Inch or metric data input and output



MetroLab is windows based software specifically designed for further mathematical analysis of measurement data of the cam profile to evaluate one degree output for lift, velocity, acceleration, jerk and radius of curvature. Different filters are provided for data smoothing. Output options include data analysis to the screen or a printer. Original data can be analyzed, smoothed and corrected for shaft eccentricity and base circle runout. The corrected data can saved for easy recall.



MetroLab - Form Analysis Software

- Menu driven and easy to use GUI's. Multilevel login allows the user to define and secure test setups and parameters.
- Single page test setup with drop down menus and graphics offer quick and error free configurations.
- · Polar representation of crankpin and journal geometry.
- Polar representation of cam profile with user defined tolerance zone.
- Software can be configured to evaluate upto twelve cam lobes per test. Each cam lobe can be individually observed and plotted.
- Individual graphical analysis of cam lobes.
- Journal evaluated for various radial parameters.



Cam profile measurement and analysis



decimal metrology

201 Berry's Plaza, 11/A Srinagar Society, Baroda, Gujarat 390 020.

- Phone: +91 265 308 3051
- Mobile: +91 99250 19770
- E-Mail: info@decimalmetrology.com
- Website: www.decimalmetrology.com





Octagon Precision (India) Pvt. Ltd.

Regd. Off.	: 3 / 19 Girija Society, M.I.T. College Road, Kothrud
-	Pune 411029. India
Plant	: S.No. 15 A/2, J7 & J8, GKD Industrial Estate,
	Nandedgaon, Sinhgad Road, Pune 411041.

- : + 91 77760 22121
- E-mail : info@octagon.co.in
 - : www.octagon.co.in

Tel.

Web